## Numerical Methods



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## Review of Calculus

Definition: A function $f$ defined on a set $X$ of real numbers has the limit $L$ at $x_{0}$, written

$$
\begin{equation*}
\lim _{x \rightarrow x_{0}} f(x)=L, \tag{1.1}
\end{equation*}
$$

if, given any real number $\epsilon>0$, there exists a real number $\delta>0$ such that $|f(x)-L|<\epsilon$, whenever $x \in X$ and $0<\left|x-x_{0}\right|<\delta$.

Definition: Let $f$ be a function defined on a set $X$ of real numbers and $x_{0} \in X$. Then $f$ is continuos at $x_{0}$ if

$$
\begin{equation*}
\lim _{x \rightarrow x_{0}} f(x)=f\left(x_{0}\right), \tag{1.2}
\end{equation*}
$$

The function is continuous on the set $X$ if it is continuous at each number in $X$.
$C(X)$ denotes the set of all functions that are continuous in $X$.

Definition: Let $\left\{x_{n}\right\}_{n=1}^{\infty}$ be an infinite sequence of real or complex numbers. The sequence $\left\{x_{n}\right\}_{n=1}^{\infty}$ has the limit $\mathbf{x}$ (converges to $\mathbf{x}$ ) if, for any $\epsilon>0$, there exists a positive integer $N(\epsilon)$ such that $\left|x_{n}-x\right|<\epsilon$, whenever $n>N(\epsilon)$. The notation

$$
\begin{equation*}
\lim _{n \rightarrow \infty} x_{n}=x, \quad \text { or } \quad x_{n} \rightarrow x \quad \text { as } \quad n \rightarrow \infty \tag{1.3}
\end{equation*}
$$

means that the sequence $\left\{x_{n}\right\}_{n=1}^{\infty}$ converges to $x$.

Theorem: If $f$ is a function defined on a set $X$ of real numbers and $x_{0} \in X$, then the following statements are equivalent:


- $f$ is continuous at $x_{0}$
- If $\left\{x_{n}\right\}_{n=1}^{\infty}$ is any sequence in $X$ converging to $x_{0}$, then $\lim _{n \rightarrow \infty} f\left(x_{n}\right)=f\left(x_{0}\right)$.

Definition: Let $f$ be a function defined in an open interval containing $x_{0}$. The function $f$ is differentiable at $x_{0}$ if

$$
\begin{equation*}
f^{\prime}\left(x_{0}\right)=\lim _{x \rightarrow x_{0}} \frac{f(x)-f\left(x_{0}\right)}{x-x_{0}} \tag{1.4}
\end{equation*}
$$

exists. The number $f^{\prime}\left(x_{0}\right)$ is called the derivative of $f$ at $x_{0}$. A function that has a derivative at each number in a set $X$ is differentiable on $X$. The derivative of $f$ at $x_{0}$ is the slope of the tangent line to the graph of $f$ at $\left(x_{0}, f\left(x_{0}\right)\right)$.


Theorem: If the function $f$ is differentiable at $x_{0}$, then $f$ is continuous at $x_{0}$.
The set of all function that have $n$ continuous derivatives on $X$ is denoted $C^{n}(X)$.

The next theorems are of fundamental importance in deriving methods for error estimation.

## Rolle's Theorem

Suppose $f \in C[a, b]$ and $f$ is differentiable on $(a, b)$. If $f(a)=f(b)$, then a number $c$ in $(a, b)$ exists with $f^{\prime}(x)=0$.



## Mean Value Theorem

If $f \in C[a, b]$ and $f$ is differentiable on $(a, b)$, then a number $c$ in $(a, b)$ exists with

$$
\begin{equation*}
f^{\prime}(c)=\frac{f(b)-f(a)}{b-a} . \tag{1.5}
\end{equation*}
$$

## Extreme Value Theorem

If $f \in C[a, b]$, then $c_{1}, c_{2} \in[a, b]$ exist with $f\left(c_{1}\right) \leq f(x) \leq f\left(c_{2}\right)$, for all $x \in[a, b]$. In addition, if $f$ is differentiable on $(a, b)$, then the numbers $c_{1}$ and $c_{2}$ occur either at the endpoints of $[a, b]$ of where $f^{\prime}$ is zero.

Definition: The Riemann integral of the function $f$ on the interval $[a, b]$ is the following limit, provided it exists:

$$
\begin{equation*}
\int_{a}^{b} f(x) d x=\lim _{\max \Delta x_{i} \rightarrow 0} \sum_{i=1}^{n} f\left(z_{i}\right) \Delta x_{i} \tag{1.6}
\end{equation*}
$$

where the numbers $x_{0}, x_{1}, \ldots, x_{n}$ satisfy $a=x_{0} \leq x_{1} \leq \ldots \leq x_{n}=b$, and where $\Delta x_{i}=$ $x_{i}-x_{i-1}$, for each $i=1,2, \ldots, n$ and $z_{i}$ is arbitrarily chosen in the interval $\left[x_{i-1}, x_{i}\right]$.

Every continuous function $f$ on $[a, b]$ is Riemann integrable on $[a, b]$. This permits us to choose, for computational convenience, the points $x_{i}$ to be equally spaced in $[a, b]$, and for each
$i=1,2, \ldots, n$, to choose $z_{i}=x_{i}$. In this case,

$$
\begin{equation*}
\int_{a}^{b} f(x) d x=\lim _{n \rightarrow 0} \frac{b-a}{n} \sum_{i=1}^{n} f\left(x_{i}\right) \tag{1.7}
\end{equation*}
$$

where the numbers are $x_{i}=a+i(b-a) / n$.

## Weighted Mean Value Theorem for Integrals

Suppose $f \in C[a, b]$, the Riemann integral of $g$ exists on $[a, b]$, and $g(x)$ does not change sign on $[a, b]$. Then there exists a number $c$ in $(a, b)$ with

$$
\begin{equation*}
\int_{a}^{b} f(x) g(x) d x=f(c) \int_{a}^{b} g(x) d x \tag{1.8}
\end{equation*}
$$

When $g(x)=1$, is the usual Mean Value Theorem for Integrals. It gives the average value of the function $f$ over the interval $[a, b]$ as

$$
\begin{equation*}
f(c)=\frac{1}{b-a} \int_{a}^{b} f(x) d x \tag{1.9}
\end{equation*}
$$




## Intermediate Value Theorem

If $f \in C[a, b]$ and $K$ is any number between $f(a)$ and $f(b)$, then there exists a number in $(a, b)$ for which $f(c)=\mathrm{K}$.

Example: $x^{5}-2 x^{3}+3 x^{2}-1=0$ has a solution in the interval $[0,1]$ ?
Consider

$$
\begin{equation*}
f(0)=-1<0<1=f(1) \tag{1.10}
\end{equation*}
$$

and $f$ is continuous, then the Intermediate Value Theorem implies that a number $x$ exists with $0<x<1$, for which $x^{5}-2 x^{3}+3 x^{2}-1=0$.


## Taylor's Theorem

Suppose $f \in C^{n}[a, b]$, that $f^{(n+1)}$ exists on $[a, b]$, and $x_{0} \in[a, b]$. For every $x \in[a, b]$, there exists a number $\xi(x)$ between $x_{0}$ and $x$ with

$$
\begin{equation*}
f(x)=P_{n}(x)+R_{n}(x), \tag{1.11}
\end{equation*}
$$

where
$P_{n}(x)=f\left(x_{0}\right)+f^{\prime}\left(x_{0}\right)\left(x-x_{0}\right)+\frac{1}{2!} f^{\prime \prime}\left(x_{0}\right)\left(x-x_{0}\right)^{2}+\cdots+\frac{1}{n!} f^{(n)}\left(x_{0}\right)\left(x-x_{0}\right)^{n}=\sum_{k=0}^{n} \frac{f^{(k)}\left(x_{0}\right)}{k!}\left(x-x_{0}\right)^{k}$
and

$$
\begin{equation*}
R_{n}(x)=\frac{f^{(n+1)}(\xi(x))}{(n+1)!}\left(x-x_{0}\right)^{n+1} \tag{1.13}
\end{equation*}
$$

Here $P_{n}(x)$ is called the nth Taylor polynomial for $f$ about $x_{0}$, and $R_{n}(x)$ is called the remainder term (or truncation error) associated with $P_{n} x$. In the case $x_{0}=0$, the Taylor polynomial is often called a Maclaurin polynomial.

The term truncation error refers to the error involved in using a truncated, or finite, summation to approximate the sum of an infinite series.


